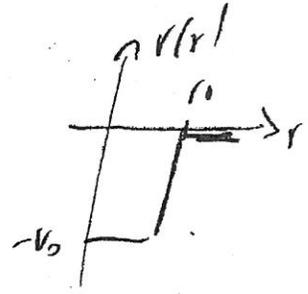


Problem Set 10 Solutions

$$1. \quad H = \frac{1}{2m} \left(p_r^2 + \frac{p_\theta^2}{r^2} \right) + V(r)$$

H indep of time, θ cyclic

$$\rightarrow E = \frac{1}{2m} \left(p_r^2 + \frac{d_\theta^2}{r^2} \right) + V(r)$$



For orbit - angle variables want bound motion,
 p_r real inside the well, so

$$E - \frac{d_\theta^2}{2mr_0^2} + V_0 > 0 \quad ; \quad E - \frac{d_\theta^2}{2mr_0^2} < 0$$

Maximum value of r is r_0 ,

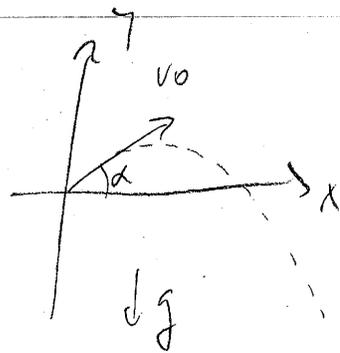
Minimum " " " is $r_- = \frac{|d_\theta|}{\sqrt{2m(E+V_0)}}$

$$\text{so } I = \frac{1}{2\pi} \oint p_r dr = \frac{1}{\pi} \int_{r_-}^{r_0} d\theta \sqrt{2m(E+V_0) - d_\theta^2/r^2}$$

$$\omega^{-1} = \frac{\partial I}{\partial E} = \frac{m}{\pi} \int_{r_-}^{r_0} \frac{dr}{\sqrt{\dots}}$$

$$= \frac{1}{2\pi} \frac{\sqrt{2m(E+V_0)r_0^2 - d_\theta^2}}{E+V_0}$$

$$2. \quad H = \frac{1}{2m} (p_x^2 + p_y^2) + mgy$$



time-independent, cyclic in x
 + separable in x, y .

- so try $S = \alpha_x x + W_1(y) - Et$

$$\rightarrow \frac{1}{2m} \left(\alpha_x^2 + \left(\frac{\partial W_1}{\partial y} \right)^2 \right) + mgy = E$$

$$W_1 = \int^y dy' \sqrt{2mE - \alpha_x^2 - 2m^2gy}$$

$$= \frac{-1}{3m^2g} (2mE - \alpha_x^2 - 2m^2gy)^{3/2}$$

The new (constant) coordinates are $\alpha_i = \frac{\partial S}{\partial \alpha_i} = p_i$
 with $\{\alpha_i\} = \{E, \alpha_x\}$ so

$$p_t = \frac{\partial}{\partial E} (\alpha_x x + W_1 - Et) = -t$$

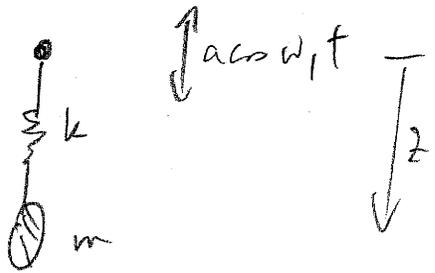
$$p_x = \frac{\partial}{\partial \alpha_x} (\alpha_x x + W_1 - Et) = \frac{x + \frac{1}{m^2g} \sqrt{2mE - \alpha_x^2 - 2m^2gy}}{\alpha_x}$$

The old coordinates are $p_i = \frac{\partial S}{\partial q_i}$

$$\text{or } p_x = \frac{\partial S}{\partial x} = \alpha_x, \quad p_y = \frac{\partial S}{\partial y} = \sqrt{2mE - \alpha_x^2 - 2m^2gy}$$

Then determine the constants α_i, p_i from the initial conditions in x, y, p_x, p_y ...

3.



$$H = p^2/2m + \frac{1}{2}k(z - a \cos \omega_1 t)^2$$

$$= \frac{p^2}{2m} + \frac{1}{2}kz^2 - ka \cos \omega_1 t + \frac{1}{2}ka^2 \cos^2 \omega_1 t$$

$$= H_0 + H_1$$

for H_0 , HJ solution is $z = \sqrt{\frac{2\alpha}{k}} \sin \omega_0 (t + \beta)$

where $\alpha \leftrightarrow$ energy, $\omega_0 = \sqrt{k/m}$

so $H_1 = -ka \cos \omega_1 t \cdot \sqrt{\frac{2\alpha}{k}} \sin \omega_0 (t + \beta)$

$$d_1 = - \frac{\partial H_1}{\partial \beta} \Big|_0 = -ka \omega_0 \sqrt{\frac{2\alpha_0}{k}} \cos \omega_1 t \cos \omega_0 (t + \beta_0)$$

$$f_1 = \frac{\partial H_1}{\partial \alpha} \Big|_0 = - \frac{ka}{\sqrt{2\alpha_0 k}} \cos \omega_1 t \sin \omega_0 (t + \beta_0)$$

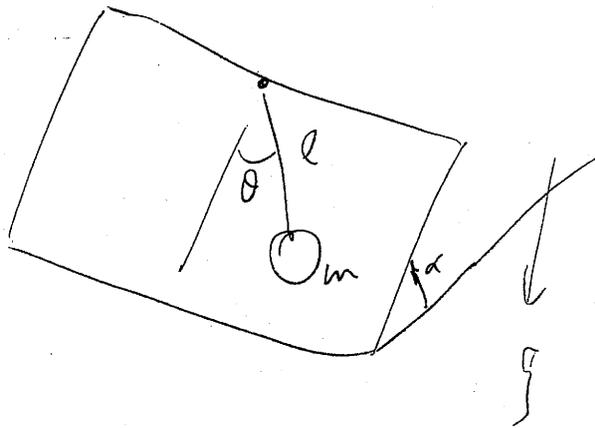
$$\rightarrow d_1 = -ka \sqrt{\frac{\alpha_0}{2m}} \left[\cos \left[(\omega_0 + \omega_1)t + \omega_0 \beta_0 \right] - \cos \left[(\omega_0 - \omega_1)t + \omega_0 \beta_0 \right] \right]$$

$$d_1 = ka \sqrt{\frac{\alpha_0}{2m}} \left[\frac{1}{\omega_0 + \omega_1} \sin \left[(\omega_0 + \omega_1)t + \omega_0 \beta_0 \right] - \frac{1}{\omega_0 - \omega_1} \sin \left[(\omega_0 - \omega_1)t + \omega_0 \beta_0 \right] \right]$$

+ similarly for f_1 .

then $z(t) = \sqrt{\frac{2}{k}} (d_0 + d_1) \sin \omega_0 (t + \beta_0 + \beta_1)$

4.



θ in plane
 α from horizontal

$$V = mgl(1 - \cos \theta) \cdot \sin \alpha$$

$$\approx \frac{1}{2} mgl \sin \alpha \cdot \theta^2$$

$$H = \frac{p^2}{2ml^2} + \frac{1}{2} mgl \sin \alpha \cdot \theta^2 = T\omega = J \sqrt{\frac{g \sin \alpha}{l}}$$

Maximum amplitude θ_{\max} when $p = 0$ or

$$\theta_{\max} = \sqrt{\frac{2J\omega}{mgl \sin \alpha}} = f(J) \cdot (\sin \alpha)^{-\frac{1}{4}}$$

If α varies slowly, $J \approx \text{constant}$, $\theta_{\max} \sim (\sin \alpha)^{-\frac{1}{4}}$

$$\text{or } \frac{\delta \theta_{\max}}{\theta_{\max}} = -\frac{1}{4} \cot \alpha \cdot \delta \alpha$$